

Quick Start Guide Battery Management System (BMS) with MPC5775B-EVB and RD33771CDSTEV

NXP evaluation boards for high-voltage battery management



Quick Start Guide

REQUIRED HARDWARE FOR THE DEMO

Board Part Number	Description	Weblink
MPC5775B-EVB	MPC5775B EVB with MC33664 TPL interface support	NXP link
RD33771CDSTEVB	MC33771C based Battery Cell Controller Evaluation board	NXP link
BATT-14CEMULATOR	14 Cell battery emulator board	NXP link
PCAN-USB adapter	CAN monitor	PHYTools

MPC5775B-EVB



BATT-14CEMULATOR



RD33771CDSTEVB



PCAN-USB



REQUIRED SOFTWARE FOR THE BMS DEMO

Item	Description	Weblink
S32 Design Studio IDE	NXP S32 Design Studio IDE for PowerPC V2.1	NXP link
MPC5775B-BatterySystem SDK	S32DS based Jump start demo software for the MPC5775B-EVB using SDK 3.0.0 with FreeRTOS	NXP link
MPC5775B-BatterySystem GUI	Graphic User Interface software to monitor battery status via CAN interface.	NXP link
Python 3.7 64-bit with PyQt5 and NumPy	Install the Python 64-bit version, then install the PyQt5 and NumPy packages	Python link

1 Download Software



Download installation software and documentation under **"Jump Start Your Design"** at nxp.com/MPC5775B-BatterySystem

Quick Start Guide

GET TO KNOW THE BMS DEMO

Note: Numbers correspond to the steps to follow for setup.

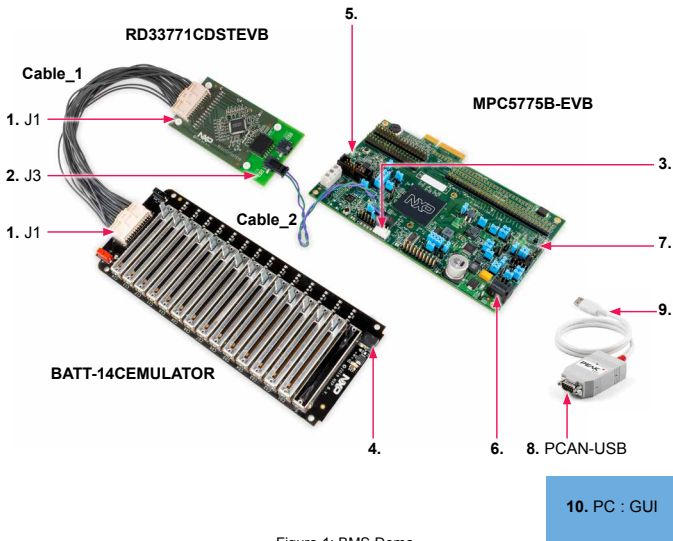


Figure 1: BMS Demo

STEP-BY-STEP INSTRUCTIONS FOR BMS DEMO SETUP

1 Connect BATT-14CEMULATOR and RD33771CDSTEVB

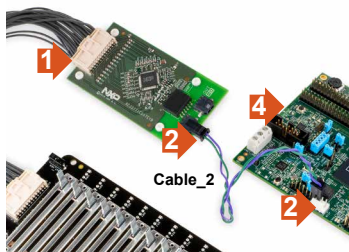
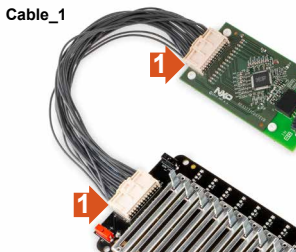
Connect the battery cell emulator board (BATT-14CEMULATOR) and the cell controller board (RDCV33771C) using Cable_1.

2 Connect RD33771CDSTEVB and MPC5775B-EVB for TPL link

Connect the cell controller board with battery management board using the Cable_2 as shown in the figure to the right. This will establish the TPL link for communication.

Either J1 or J2 can be connected to the RD33771CDSTEVB.

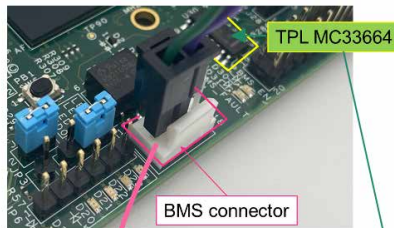
User must connect positive (+) terminal of MPC5775B-EVB's BMS interface connector (J118 – pin 3,4) to BMS cell controller module positive (+) terminal and negative terminal to negative terminal as shown in the next slide.



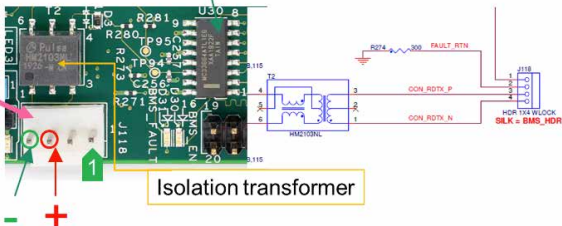
Quick Start Guide

BMS APPLICATION SPECIFIC CONNECTIONS

APPLICATION SPECIFIC ITEM	MPC5775B-EVB	MPC5775E-EVB
Battery management connector	J118	Not supported



PIN	DESCRIPTION	J118 REMARKS
1	FAULT_IN	For TPL connection use pin 3 and 4. Connect the positive to positive and negative to negative.
2	FAULT_RTN	
3	TPL_P positive terminal	
4	TPL_N negative terminal	



STEP-BY-STEP INSTRUCTIONS FOR BMS DEMO SETUP CONTINUED

3 Power up BATT-14CEMULATOR & RD33771CDSTEV

Connect the power supply to the BATT-14CEMULATOR. Powering the emulator board also powers the RDCV33771C cell controller board.



4 Connect the USB serial cable to MPC5775B-EVB and PC

Connect the micro-USB cable to J116 micro-USB port for OpenSDA connection for programming and debug.

Connect the USB side to the computer.

Refer MPC5775B-EVB QSG for more information.



STEP-BY-STEP INSTRUCTIONS FOR BMS DEMO SETUP CONTINUED

5 Power the MPC5775B-EVB

Connect 12V power supply to power socket on the Development board.

Make sure the status LEDs D14, D15, D16 and D32 for voltage levels 3.3V, 5V, 1.25V and 12V supply respectively are glowing green on the board.

6 Connect the CAN with PCAN tool

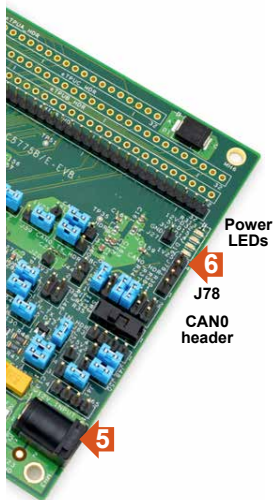
Connect CAN High and Low signals of J78 to PCAN tool CAN high and low.

MPC5775B-EVB:

J78 pin 2 is CAN0_High

J78 pin 3 is CAN0_Low

PIN	DESCRIPTION	REMARKS
1	5V	TJA1145T PHY
2	CAN1_0H	need to be enabled
3	CAN1_0L	via DSP1_B, Chip
		select CSB1. Use
		J58 & J60 for CAN
4	GND	module selection. By
		default connected to
		FlexCAN_A/MCAN0.

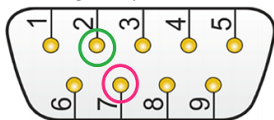


STEP-BY-STEP INSTRUCTIONS FOR BMS DEMO SETUP CONTINUED

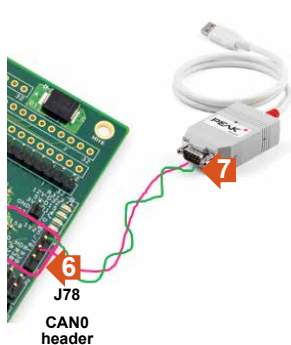
7 Connect the CAN with PCAN tool

Connect the CAN_H and CAN_L signals of J78 of MPC5775B-EVB to PCAN USB CAN_H (pin 7) and CAN-L (pin 2) via two jumper cables.

Pin assignment 9-pole connector male:



Pin	Configuration	Pin	Configuration
1	+12V/+5V/Not Connected	6	CAN-GND/Not Connected
2	CAN-L	7	CAN-H
3	CAN-GND/Not Connected	8	Not Connected
4	Not Connected	9	+12V/+5V/Not Connected
5	Not Connected		



STEP-BY-STEP INSTRUCTIONS FOR BMS DEMO SETUP CONTINUED

8 Import the MPC5775B_BMS_SDK_SW project to S32DS

Run the S32DS for PowerPC 2.1 and follow the steps “a to f” to import the MPC5775B_BMS_SDK_SW project.

The screenshot illustrates the process of importing a project into the Eclipse IDE. The main window shows the Eclipse menu bar with the 'File' menu open, and the 'Import...' option highlighted. A red arrow labeled 'a' points to the 'File' menu, and another red arrow labeled 'b' points to the 'Import...' option.

The 'Import' dialog box is open, showing the 'Import Projects' section. The 'Select root directory:' field is empty, and a red arrow labeled 'd' points to the 'Browse...' button. The 'Projects:' list is empty. The 'Options' section has 'Search for nested projects' checked. The 'Working sets' section has 'Add project to working set' checked. A red arrow labeled 'c' points to the 'Next >' button.

The 'Browse For Folder' dialog box is open, showing the file system tree. The 'mpc5775b_bms_sdk' folder is selected, and a red arrow labeled 'e' points to the 'OK' button. The 'Folder:' field contains the path 'mpc5775b_bms_sdk'.

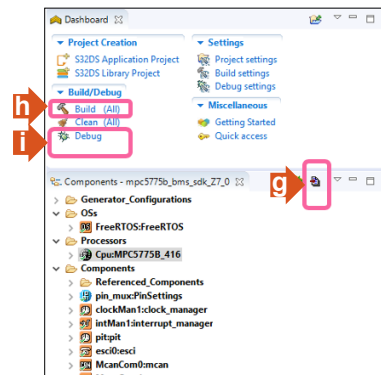
The 'Import Projects' dialog box is shown again at the bottom, with a red arrow labeled 'f' pointing to the 'Finish' button.

STEP-BY-STEP INSTRUCTIONS FOR BMS DEMO SETUP CONTINUED

9 Generate Processor Expert Codes and Compile the binary image

Then build and run the program.

Follow the steps “g” to “i” to generate the processor expert codes, compile and build the image. Refer the MPC5775B-E EVB QSG for debug/flash the image.



10 Connect the PCAN tool USB to the PC

Connect the USB connector of PCAN tool to the computer USB port.



HOW TO RUN YOUR FIRST HELLO WORLD PROGRAM CONTINUED

11 Run the GUI software

Open the windows “Command Prompt” and execute the “Py Main.py” in the command shell.

“Main.py” python file included in the GUI folder.

Make sure you first install the Python 3.7 64-bit version and necessary packages PyQt5 and NumPy prior to the above step. Refer the readme file in the downloaded software GUI folder.

```
ca Command Prompt 5.2(Virtualizer Runtime) - Py Main.py
```

```
C:\Users\nxa20245\Downloads\MPC5775B-PDC\Powertrain domain controller V 1.5.0\Sk\GUI>Py Main.py
```

HOW TO RUN YOUR FIRST HELLO WORLD PROGRAM CONTINUED

12 Setup the GUI link

- Select CAN1
- Set CAN baud rate to 500Kbps
- Click "Start", now the CAN link establish with the main controller board
- Click "OK"
- Initiate global reset to BMS system by clicking "Global Reset"
- User able to observe the battery pack information shown in next slide

The screenshot displays the NXP HVBMS Solution v1.7.0 GUI. The interface is divided into several sections:

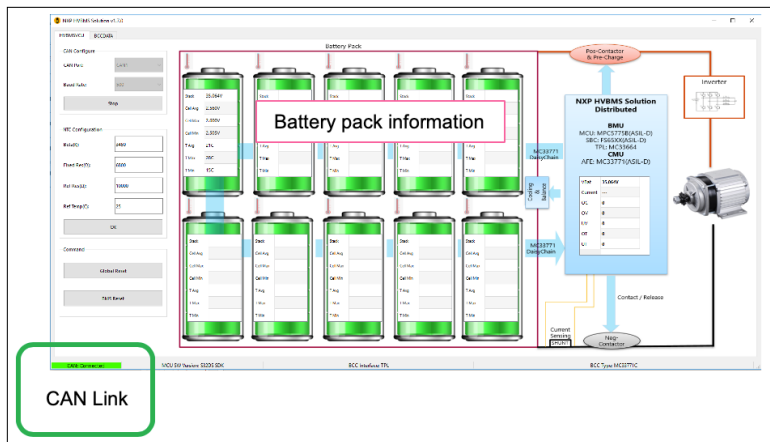
- CAN Configuration:** Includes a dropdown menu for 'CAN Port' (set to CAN1), a dropdown for 'Baud Rate' (set to 500), and a 'Start' button. Red arrows labeled 'a', 'b', and 'c' point to these elements.
- ITC Configuration:** Includes input fields for 'Beta(k):' (3450), 'Fixed Res(Ω):' (6300), 'Ref Res(Ω):' (10000), and 'Ref Temp(°C):' (25). A red arrow labeled 'd' points to the 'OK' button below this section.
- Command:** Includes 'Global Reset' and 'BMS Reset' buttons. A red arrow labeled 'e' points to the 'Global Reset' button.
- Battery Pack Status:** Two battery pack icons are shown on the right. Each icon has a green bar at the top and a blue bar at the bottom. The top battery pack has a red arrow pointing to its top. The bottom battery pack has a blue arrow pointing to its bottom.

At the bottom of the GUI, there is a status bar with 'CAN: Not Connected' on the left and 'MCU SW Version: S1205 SDK' on the right.

Quick Start Guide

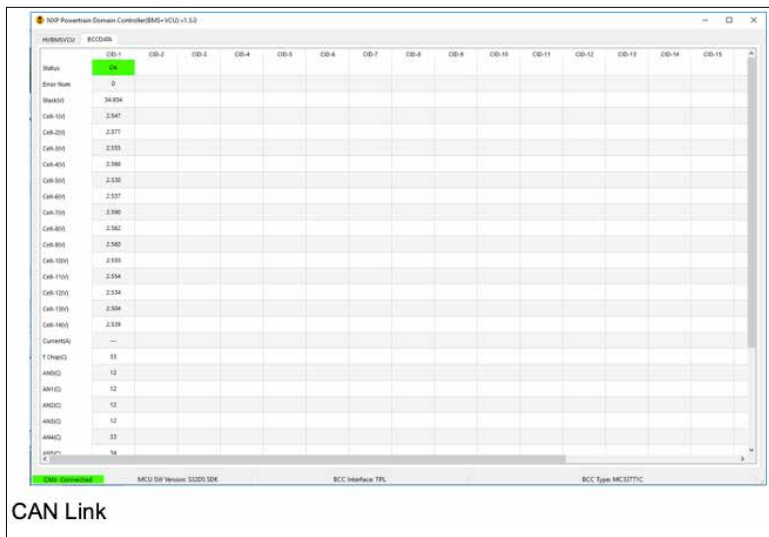
GUI INTERFACE 1/2

Figure below shows the GUI interface after communication has been established.



GUI INTERFACE 2/2

Adjust the battery levels via BATT-14CEMULATOR and observe the GUI for individual cell data in "BCCDATA" tab.



CAN Link

REFERENCES

DOCUMENT	DESCRIPTION	LOCATION
MPC5775B-E-EVB-QSG	Quick Start Guide of MPC5775B-EVB	NXP web site
AN12875	Getting Started with MPC5775E-EVB and MPC5775B-EVB	NXP web site
MPC5775E RM	MPC5775E/MPC5775B Reference Manual	NXP web site
MPC5775E DS	MPC577E/MPC5775B Data Sheet	NXP web site
OpenSDA	OpenSDA User's guide	NXP web site
S32DS	S32 Design Studio for Power Architecture v2.1 - Windows/Linux	NXP web site
MC33FS6520LAE	MC33FS6520 System Basis Chip (Power supply and drivers) Data Sheet	NXP web site
FS65SBC-SDK-SW	FS6500/FS4500 Generic Embedded Software Driver (Software Development Kit)	NXP web site
TJA1100	TJA1100 100BASE-T1 PHY For Automotive Ethernet	NXP web site
TJA1145	High-speed CAN transceiver for partial networking	NXP web site
MC33664_SDS	Isolated Network High-Speed Transceiver Short Data Sheet	NXP web site
MC33664	Isolated Network High-Speed Transceiver Full Data Sheet	NXP web site
MC33771C	Battery Cell Controller Full Data Sheet	NXP web site
RD33771CDSTEVb	Evaluation Board for MC33771C BCC with Isolated Daisy Chain Communication	NXP web site
BATT-14CEMULATOR	14-Cell Battery Pack Emulator to Supply MC33771C BCC EVBs	NXP web site
HM2102NL	Pulse Electronics Dual BMS transformer	Pulse Electronics
HM2103NL	Pulse Electronics Single BMS transformer	Pulse Electronics



SUPPORT

Visit www.nxp.com/support for a list of phone numbers within your region.

WARRANTY

Visit www.nxp.com/warranty for complete warranty information.

AUTOMOTIVE COMMUNITY

Visit <https://community.nxp.com/community/s32>

PRODUCT COMMUNITY

Visit <https://community.nxp.com/community/s32/MPC5xxx>



Get Started

Download installation software and documentation under “**Jump Start Your Design**” at nxp.com/MPC5775B-BatterySystem

nxp.com/MPC5775B-BatterySystem

NXP and the NXP logo are trademarks of NXP B.V. All other product or service names are the property of their respective owners. The Bluetooth® word mark and logos are registered trademarks owned by Bluetooth SIG, Inc. and any use of such marks by NXP Semiconductors is under license. © 2020 NXP B.V.